

### CONTACT

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ryanp543.github.io/portfolio/

## SKILLS .

#### Software

SolidWorks
Autodesk Inventor
Autodesk Fusion 360
Autodesk Eagle
Python
C++
MATLAB
Mathematica
Arduino/Teensy
FEA (SolidWorks, COMSOL)
HSM Works (CAM)
MasterCAM
ROS 1 and 2

#### **Manufacturing**

Inkscape

Milling, Lathework, Drilling
Plastic Mold Casting
Thermoforming
Laser Cutting
Waterjetting
Sheet Bending
CNC (3- and 5-Axis)
3D Printing (FDM, SLA)
Soldering
PCB Design/Reflow Oven
1000+ Hours of Machining
Experience

## RESEARCH

## **Graduate Research Assistant**Bioinstrumentation Laboratory | MIT

Sept 2019-present

- Developed a climbing robot that uniquely combines a wheeled drive with modular underactuated tendon-driven grasping arms to maximize adaptability to different column sizes.
- Developed a novel twisted-winching string actuator offering both high force and high displacement modes for tendon-driven robotic applications.
- Developed a miniaturized modular tool changer and custom robotic arm on a rover for agricultural monitoring and maintenance.
- Developed an impedance analyzer, pH probe, thermal camera, and spectroscopy tool for agricultural measurement purposes.
- Developed a universal Lyapunov-based Python library to rapidly generate stable PID gains for flexible base manipulators.

# **Undergraduate Researcher**Biomechatronics Laboratory | UCLA

Feb 2016-June 2019

- Developed a motor bank and wrist adapter to expand the lab's tendondriven robotic hand from one to three fingers and merge it with Barrett Technology's WAM robotic arm infrastructure.
- Designed and 3D printed pressure-sensitive instrumented objects for a haptic search-and-retrieval Office of Naval Research project.

# **Undergraduate Researcher**Robotics and Mechanisms Laboratory | UCLA

Sept 2017-June 2019

- Designed, machined, and assembled the legs of a large mobile hexapod robot made to carry equipment for ordnance retrieval and disposal.
- Fabricated parts for the four-legged ALPHRED and non-anthropomorphic biped robots as the go-to undergraduate lab machinist.

# **Undergraduate Researcher**Flexible Research Group | UCLA

June 2018-June 2019

• Developed an actively controlled metamaterial that utilized phase changes to achieve programmable stiffness properties.

## **EDUCATION**

# **Ph.D. Candidate in Mechanical Engineering** *Massachusetts Institute of Technology*

June 2021-present

- GPA: 4.8 out of 5.0
- Qualifying Exams: Robotics, Product Design, Manufacturing
- Courses: Underactuated Robotics, New Enterprises (Sloan), Manufacturing Processes and Systems, Product Design and Development

# M.S. in Mechanical Engineering Massachusetts Institute of Technology

Sept 2019-May 2021

• Courses: Bioinspired Robotics, Advanced Instrumentation, Machine Design, Advanced System Dynamics/Control, Intro to Robotics

## **B.S. in Mechanical Engineering**University of California, Los Angeles

Sept 2015-June 2019

- GPA: 3.871 out of 4.0, GRE: 168 Q/159 V/6.0 AWA
- Courses: Dynamics, Statics, Materials, Electrical Circuits, Modeling of Dynamic Systems, Compliant Mechanisms, Feedback and Control Systems

### PUBLICATIONS/PATENTS

# A Multimodal Twisted-Winching String Actuator with a Passive Automatic Transmission: Design and Validation

R Poon, V Padia, I Hunter | 2025

International Conference on Control, Automation, and Robotics (ICCAR)

# Control and Analysis of a Multimodal Twisted-Winching String Actuator with Embodied Sensing

R Poon, V Padia, I Hunter | 2025

IEEE-RAS International Conference on Soft Robotics (RoboSoft)

## A Novel Twisted-Winching String Actuator for Robotic Applications: Design and Validation

R Poon, V Padia, I Hunter | 2025

IEEE International Conference on Robotics and Automation (ICRA)

### **Hybrid Twisted String Actuator-Winch System**

V Padia, R Poon, I Hunter | 2023

U.S. Patent Application No. 63/694,401

# Streamlined Tuning Procedure for Stable PID Control of Flexible-Base Manipulators

MA Begin, R Poon, I Hunter | 2021

IEEE Robotics and Automation Letters 6 (4), 7413-7420

# Phase-Changing Metamaterial Capable of Variable Stiffness and Shape Morphing

R Poon, JB Hopkins | 2019

Advanced Engineering Materials 21 (12), 1900802

### STUDENT ORGANIZATIONS

## **Mentor** *Makerworkshop* | *MIT*

Sept 2019-present

- Supervise graduate student-run makerspace on campus ensuring safe operation of all machines and tools.
- Instruct new members and mentors on usage and safety of the tools in the shop, including mill, lathe, waterjet, laser cutter, and 3D printer.

#### President

Sept 2015-June 2019

### 3D For Everyone (3D4E) | UCLA

- Founded a 9-week CAD and 3D printing workshop for 45 new members.
- Landed three 3D printer sponsorships and ~\$5000 of funding.
- Designed and printed the "Spock" basketball prosthetic hand with the UCLA women's basketball team for children with limb differences.
- Directed and participated in the Angel City Sports adaptive sports equipment, musical instruments outreach, and wind turbine projects.

### **Technical Vice President**

Sept 2015-June 2019

#### American Society of Mechanical Engineers | UCLA

- Led developments of the 60 lb 2016 and 2017 flagship battlebots.
- Manufactured a 3 lb battlebot featuring dual horizontal spinners.
- Managed overall club operations for 80 engineering student members, training them in CAD, machining, robotics, and professional development.

## AWARDS

- 2021 Wunsch Foundation Silent -Hoist and Crane Award
  - Magna Cum Laude -
  - Jack Waldron Scholarship -
  - Harley L. Wood Scholarship -
    - Arconic Scholarship -
    - Dean's Honor List -
- Outstanding B.S. in MechE Award -

### - WORK FXPFRIFNCF -

## Mechanical Engineering Intern

Made In Space | June 2017-Sept 2017

- Upgraded and modified components of the additive manufacturing facility (AMF) 3D printer on the International Space Station.
- Designed and prototyped the Satellite Manufacturing Machine, which boasts multimaterial printing and electronic component placement.

### Mechanical Design Intern

AIO Robotics | Oct 2016-Jan 2017

 Collaborated with Florida-based club Handling the Future to design and 3D print a prosthetic hand mimicking the curvature of human hands.

## – other –

# **Competitive Compound Archer** *UCLA and MIT* | 2015-present

- Compete at the regional and national levels.
- 3rd place at the 2016 CA State Indoor Championships and at the 2016 West Regional Outdoor Collegiate Championships.
- 1st place on the male compound team at West Regionals.

### ENGINEERING PORTFOLIO

ryanp543.github.io/portfolio/